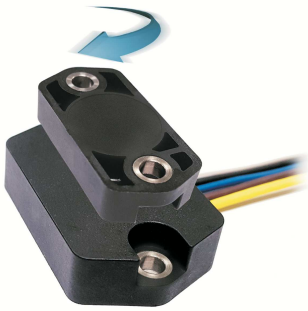


## PS2P-CON.

# Rotary concentric touchless sensor



### Main features.

- True touchless operation: free from wear and tear.
- Low profile & robust magnetic design that easily adapts to your design.
- Selectable output: analogue (ratiometric) or PWM. SPI upon request.
- Programmable angular range up to 360 degrees.
- Nominal air gap: 3mm between plastic parts.
- Maximum air gap: 5mm. For higher air gap: check availability.
- Maximum magnet radial offset allowed:  $\pm 3$ mm.  
(Measured directly on non-ferromagnetic material. For other configurations check with Piher.)
- Resolution: analogue & PWM: 12 bits / SPI: 14 bits.
- Linearity:  $\pm 1\%$  absolute ( $\pm 0.5\%$  upon request).
- Over voltage protection.
- Reverse voltage protection.
- Supply voltage up to 25V.
- Programmable Linear Transfer Characteristic.  
(Some positive slopes & one negative slope can be programmed in the same transfer characteristic; up to 4 programmable points)
- Unlimited mechanical life.
- High vertical & lateral tolerance to magnet misalignment.
- Simple, redundant and full redundant versions available.
- Sealed for harsh environments.
- Operating temperature:  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .
- Self-diagnostic features.

### Sensing the position, avoiding contact.

The concentric touchless linear sensors create immunity to magnet's misalignment that negatively impacts operational performance and results in labour intensive maintenance programmes. It complements our linear and variable air-gap touchless series of non-contact angular rotary position sensors.

The magnet is attached to the moving parts whose displacement is to be measured, such as hydraulic/pneumatic controls or gear selector, and the electronics module is fixed to the chassis (or vice versa).

As absolute sensors, they will not lose the values even after a power failure.

All Piher touchless sensors are compact, sealed, low-profile, yet extremely rugged and can be custom-engineered to fit customer's specifications and existing mechanical assemblies.

### Description.

Something that is truly contactless. One magnet, One electronics module. No gears. Nothing to wear out over a lifetime.

A sensor that will deliver the same level of precision and stability throughout its life as the first day it was installed -despite extremes of vibration, shock, temperature and contamination.

Something that is easy to assemble -delivering additional cost reduction on the production line.

Something that can be fitted anywhere on the pivoting shaft, giving engineers the flexibility to be creative.

Our touchless sensor is Piher Sensing Systems at its best, packaging its core technology -slimline magnetic Hall Effect sensing- into something truly original.



Big vertical & lateral magnet misalignment allowed.

## Touchless working principle



Measurement of angular position using variation of magnetic field amplitude induced by the displacement of a moving magnet has been intensively developed over the last fifteen years. However, these solutions have limits in terms of angular range and temperature influence.

The technology used by Piher is only sensitive to the flux density coplanar with the IC surface.

The angular information is computed from both vectorial components of the flux density (i.e. BX and BY) of a magnet. Then an output signal proportional to the decoded angle is produced.

- Agriculture.
- Construction & forestry.
- Material handling.
- Lifts & cranes.
- Marine.
- Medical.



PS2P-CON. Dimensions

# Rotary concentric touchless sensor

Dimensions in mm. Drawings may not be to scale.  
Number and function of wires pictured in this datasheet may vary according to the selected output configuration.



\* Nominal air gap: 3mm  
For higher air gap please contact [sales@piher.net](mailto:sales@piher.net)



# PS2P-CON. Ordering information

## Rotary concentric touchless sensor

Part number example:

Redundant type with analog output, C0003 output function, 360° rotational feedback and 5V supply : PS2P-CON-CE-M001-2AA-C0003-ERA360-05



Free online expert advice at <http://piher.net/configurator/2018/04/13/touchless-sensor-configurator/>

(1) Magnet Model



(2) Output

The analog output is a ratiometric output, proportional to:  
 - For supply voltage 5V: to input supply voltage.  
 - For supply voltage RE: to 5V.

(3) Output function

Other output functions available check availability. In the How To Order reference, enter CXXXX meanwhile the new output function reference is not defined.

Standard output functions:



(4) Electrical rotational angle

ERA = electrical rotational angle measured in degrees. Examples:  
 ERA015 = 15 degrees electrical rotational angle (minimum).  
 ERA150 = 150 degrees electrical rotational angle.  
 ERA360 = 360 degrees electrical rotational angle.

(5) Voltage supply

05: 5V ±10%  
 RE: 7V - 25V  
 RE not available for full redundant versions.

(6) PWM frequency

Leave empty if no applicable. Default frequency is 200 Hz  
 For redundant versions, please, write both frequencies: -XXXXFXXX

Ferromagnetic parts close to the sensor environment may modify the performance of the sensor. Therefore, this has to be communicated to Piher for prior analysis.

No external magnetic perturbations are considered on the application where the sensor is mounted. If so, amplitude and direction of flux density generator type and characteristics (magnet, cable, motor...) must be notified to Piher for a magnetic simulation analysis update.

The product information in this catalogue is for reference purposes. Please consult for the most up to date and accurate design information.

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