## **NTS0304E**

# 4-bit dual supply translating transceiver; open drain; auto direction sensing

Rev. 1 — 01 February 2019

**Product data sheet** 

### 1. General description

The NTS0304E is a 4-bit, dual supply translating transceiver family with auto direction sensing, that enables bidirectional voltage level translation. It features eight 1-bit input-output ports (A and B), one output enable input (OE) and two supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ).  $V_{CC(A)}$  can be supplied at any voltage between 0.95 V and 3.6 V.  $V_{CC(B)}$  can be supplied at any voltage between 1.65 V and 5.5 V. This flexibility makes the device suitable for translating between any of the voltage nodes (0.95 V, 1.2 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins A and OE are referenced to  $V_{CC(A)}$  and pin B is referenced to  $V_{CC(B)}$ . A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state.

#### 2. Features and benefits

- Wide supply voltage range:
  - ◆ V<sub>CC(A)</sub>: 0.95 V to 3.6 V and V<sub>CC(B)</sub>: 1.65 V to 5.5 V
- No power-sequencing required
- Maximum data rate
  - Open-drain: 2 Mbps
  - Push-pull: 20 Mbps
- Longer one-shot pulse for driving larger capacitive loads with much reduced ringing and overshoot
- A-side and OE inputs accept voltages up to 3.6 V and are 3.6 V tolerant
- B-side inputs accept voltages up to 5.5 V and are 5.5 V tolerant
- ESD protection:
  - ◆ IEC 61000-4-2 Class 4, 8 kV contact for B-side port
  - ◆ HBM JESD22-A114E Class 2 exceeds 2000 V for both ports
  - ◆ CDM JESD22-C101E exceeds 1000 V for both ports
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Package options: TSSOP14 and WLCSP12
- Specified from –40 °C to +125 °C

### 3. Applications

- I<sup>2</sup>C/SMBus, UART
- GPIO



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## 4. Ordering information

Table 1. Ordering information

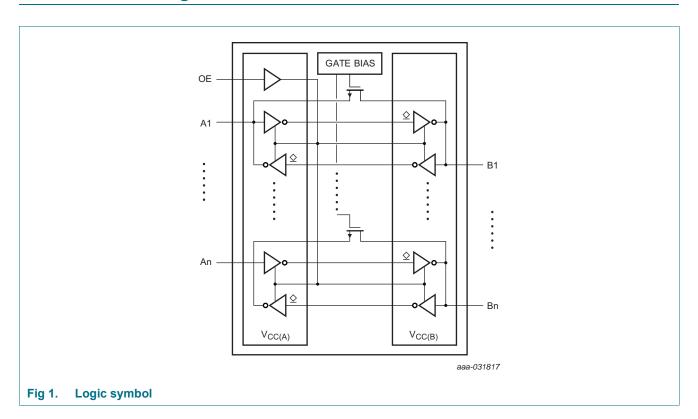
Type number	Topside	Package	Package						
	marking	Name	Description	Version					
NTS0304EUK	S4	WLCSP12	wafer level chip scale package; 12 balls with 0.4 mm pitch; 1.42 x 1.97 x 0.525 mm	SOT1390-10					
NTS0304EPW	NTS0304	TSSOP14	plastic thin shrink small outline package; 14 leads; body width 4.4 mm	SOT402-1					

### 4.1 Ordering options

Table 2. Ordering options

Type number	Orderable part number	Package	Packing method	Minimum order quantity	Temperature
NTS0304EUK	NTS0304EUKZ	WLCSP12	reel 7" q1/t1 *special mark chips dp	4000	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$
NTS0304EPW	NTS0304EPWJ	TSSOP14	reel 13" q1/t1 *standard mark smd	2500	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$

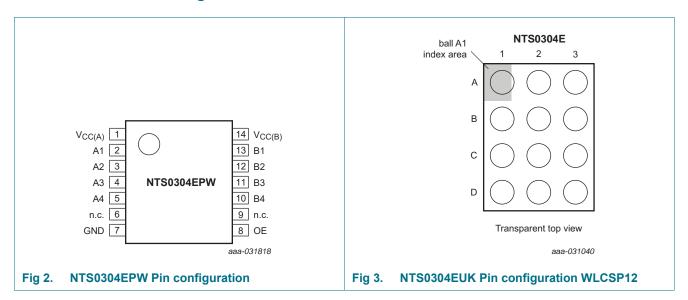
## 5. Functional diagram



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### 6. Pinning information

### 6.1 Pinning



#### 6.2 Pin description

Table 3. NTS0304E Pin description

Symbol	Pin	Ball	Description
	SOT402-1	WLCSP12	
V <sub>CC(A)</sub>	1	B2	supply voltage A
A1, A2, A3, A4	2, 3, 4, 5	A3, B3, C3, D3	data input or output (referenced to V <sub>CC(A)</sub> )
n.c.	6, 9	-	not connected
GND	7	D2	ground (0 V)
OE	8	C2	output enable input (active HIGH; referenced to V <sub>CC(A)</sub> )
B4, B3, B2, B1	10, 11, 12, 13	D1, C1, B1, A1	data input or output (referenced to V <sub>CC(B)</sub> )
V <sub>CC(B)</sub>	14	A2	supply voltage B

## 7. Functional description

Table 4. Function table[1]

Supply voltage		Input	Input/output	put		
$V_{CC(A)}$ $V_{CC(B)}$		OE	Α	В		
0.95 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	L	Z	Z		
0.95 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	Н	input or output	output or input		
GND[2]	GND[2]	X	Z	Z		

<sup>[1]</sup> H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

<sup>[2]</sup> When either  $V_{CC(A)}$  or  $V_{CC(B)}$  is at GND level, the device goes into power-down mode.

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### 8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A			-0.5	+4.6	V
V <sub>CC(B)</sub>	supply voltage B			-0.5	+6.5	V
VI	input voltage	A port and OE input	[1][2]	-0.5	+6.5	V
		B port	[1][2]	-0.5	+6.5	V
Vo	output voltage	Active mode	[1][2]			
		A or B port		-0.5	V <sub>CCO</sub> + 0.5	V
		Power-down or 3-state mode	[1]			V
		A port		-0.5	+4.6	
		B port		-0.5	+6.5	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < 0 V		-50	-	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V		-50	-	mA
lo	output current	V <sub>O</sub> = 0 V to V <sub>CCO</sub>	[2]	-	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>		-	100	mA
$I_{GND}$	ground current			-100	-	mA
T <sub>stg</sub>	storage temperature			-65	+150	°C

<sup>[1]</sup> The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

## 9. Recommended operating conditions

Table 6. Recommended operating conditions[1][2]

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A	[2]	0.95	3.6	V
V <sub>CC(B)</sub>	supply voltage B		1.65	5.5	V
V <sub>I_EN</sub>	EN input voltage		-0.3	V <sub>CC(A)</sub> +0.3	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
TJ	junction temperature	[3]	-40	+85	°C
Δt/ΔV	input transition rise and fall rate	A or B port; push-pull driving			
		$V_{CC(A)} = 0.95 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	10	ns/V
		OE input			
		V <sub>CC(A)</sub> = 0.95 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	10	ns/V

<sup>[1]</sup> The A and B sides of an unused I/O pair must be held in the same state, both at V<sub>CCI</sub> or both at GND.

<sup>[2]</sup> V<sub>CCO</sub> is the supply voltage associated with the output.

<sup>[2]</sup>  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

<sup>[3]</sup> The T<sub>J</sub> limits shall be supported by proper thermal PCB design taking the power consumption and the thermal resistance as listed in Table 7 into account.

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### 10. Thermal characteristics

Table 7. Thermal resistance information

Symbol	Rating		NTS0304EUK (WLCSP12)
$R_{\theta JA}$	Junction to ambient	114.9	57.8
ΨЈТ	Junction to top characterization	1.6	0.2

### 11. Static characteristics

Table 8. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 ℃.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
l <sub>l</sub>	input leakage current	OE input; $V_I$ = 0 V to 3.6 V; $V_{CC(A)}$ = 0.95 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V	-	-	±1	μΑ
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$ ; $V_{CC(A)} = 0.95 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	-	±1	μΑ
Cı	input capacitance	OE input; $V_{CC(A)} = 3.3 \text{ V}$ ; $V_{CC(B)} = 3.3 \text{ V}$	-	1	-	pF
C <sub>I/O</sub>	input/output	A port	-	4	-	pF
	capacitance	B port	-	7.5	-	pF
		A or B port; $V_{CC(A)} = 3.3 \text{ V}$ ; $V_{CC(B)} = 3.3 \text{ V}$	-	11	-	pF

<sup>[1]</sup> V<sub>CCO</sub> is the supply voltage associated with the output.

Table 9. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 ℃.

			V <sub>CC(B)</sub>						
	1.65 V	1.65 V		2.5 V		3.3 V		5.0 V	
V <sub>CC(A)</sub>	I <sub>CC(A)</sub>	I <sub>CC(B)</sub>	Unit						
0.95 V	0.1	0.1	0.1	0.5	0.1	0.5	0.1	3	μΑ
1.2 V	0.1	0.1	0.1	0.5	0.1	0.5	0.1	3	μΑ
1.8 V	-	-	0.1	0.5	0.1	0.5	0.1	3	μΑ
2.5 V	-	-	0.2	0.5	0.1	0.5	0.1	3	μΑ
3.3 V	-	-	-	-	0.1	0.1	0.1	2	μΑ

## 4-bit dual supply translating transceiver; open drain; auto direction sensing

Table 10. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		-40 °C t	o +85 °C	–40 °C to	+125 °C	Unit
				Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	A port						
	input voltage	V <sub>CC(A)</sub> = 0.95 V to 1.65 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	[1]	V <sub>CCI</sub> - 0.2	-	V <sub>CCI</sub> - 0.2	-	V
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V	[1]	V <sub>CCI</sub> – 0.4	-	V <sub>CCI</sub> - 0.4	-	٧
		B port						
		V <sub>CC(A)</sub> = 0.95 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	[1]	V <sub>CCI</sub> – 0.4	-	V <sub>CCI</sub> - 0.4	-	V
		OE input						
		V <sub>CC(A)</sub> = 0.95 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		0.65V <sub>CC(A)</sub>	-	0.65V <sub>CC(A)</sub>	CC(A) -	٧
$V_{IL}$	LOW-level	A or B port						
input voltage	V <sub>CC(A)</sub> = 0.95 V to 1.65 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	0.13	-	0.13	V	
	V <sub>CC(A)</sub> = 1.65 V to 3.6 V; V <sub>CC(B)</sub> = 2.3 V to 5.5 V		-	0.15	-	0.15	٧	
		OE input						
		V <sub>CC(A)</sub> = 0.95 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	0.35V <sub>CC(A)</sub>	-	0.35V <sub>CC(A)</sub>	V
V <sub>OHA</sub>	HIGH-level	I <sub>O</sub> = -20 μA						
	output voltage	V <sub>CC(B)</sub> = 1.65 V to 5.5 V; V <sub>CCI</sub> = V <sub>CC(B)</sub> - 0.4 V	[2]					
		V <sub>CC(A)</sub> = 1.65 V to 3.6 V	[2]	0.8V <sub>CC(A)</sub>	-	0.75V <sub>CC(A)</sub>	-	V
		V <sub>CC(A)</sub> = 0.95 V to 1.65 V	[2]	0.65V <sub>CC(A)</sub>	-	0.62V <sub>CC(A)</sub>	-	V
V <sub>OHB</sub>	HIGH-level	I <sub>O</sub> = -20 μA						
	output voltage	$V_{CC(A)} = 0.95 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V};$ $V_{CCI} = V_{CC(A)} - 0.2 \text{ V}$	[2]	0.8V <sub>CC(B)</sub>	-	0.75V <sub>CC(B)</sub>	-	V
$V_{OL}$	LOW-level	A or B port; I <sub>O</sub> = 1 mA	[2]					
	output voltage	$V_{I} \le 0.15 \text{ V};$ $V_{CC(A)} = 0.95 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	0.30	-	0.30	V
lı	input leakage current	OE input; V <sub>I</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 0.95 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	±2	-	±12	μА
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$ ; $V_{CC(A)} = 0.95 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	[2]	-	±2	-	±12	μА

## 4-bit dual supply translating transceiver; open drain; auto direction sensing

Table 10. Static characteristics ... continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		-40 °C 1	to +85 °C	-40 °C to	o +125 °C	Unit
				Min	Max	Min	Max	
I <sub>CC</sub>	supply current	$V_I = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$	<u>[1]</u>					
	I <sub>CC(A)</sub>							
	$V_{CC(A)} = 0.95 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	2.4	-	15	μА	
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V		-	2.2	-	15	μΑ
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V		-	-1	-	-8	μΑ
		I <sub>CC(B)</sub>						
		$V_{CC(A)} = 0.95 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	18	-	51	μА
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V		-	-1	-	-5	μΑ
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V		-	18	-	46	μΑ
		$I_{CC(A)} + I_{CC(B)}$						
		$V_{CC(A)} = 0.95 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	14.4	-	59	μА

<sup>[1]</sup>  $V_{CCI}$  is the supply voltage associated with the input.

<sup>[2]</sup>  $V_{CCO}$  is the supply voltage associated with the output.

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### 12. Dynamic characteristics

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit, see Figure 6; for wave forms, see Figure 4 and Figure 5.

Symbol	Parameter	Conditions				Vo	C(B)			Unit
					1.8 V		3 V	5.0 V		
				Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	0.95V									
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B		-	20	-	11.1	-	12.3	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B		-	14.8	-	12.5	-	12.2	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A		-	9.2	-	5.2	-	5.2	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A		-	8.8	-	2.9	-	1.4	ns
t <sub>en</sub>	enable time	OE to A; B		-	200	-	200	-	200	ns
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	100	-	100	-	100	ns
		OE to B; no external load	[2]	-	100	-	100	-	100	ns
		OE to A		-	250	-	250	-	250	ns
		OE to B		-	220	-	220	-	220	ns
t <sub>TLH</sub>	LOW to HIGH	A port		6.0	15.3	2.2	15.1	1.8	11.1	ns
	output transition time	B port		6.0	17.0	4.0	14.0	4.0	20.0	ns
t <sub>THL</sub>	HIGH to LOW	A port		0.9	18.0	0.7	9.0	0.6	9.0	ns
	output transition time	B port		1.6	22.0	2.8	10.7	3.2	14.2	ns
t <sub>W</sub>	pulse width	data inputs		49	-	49	-	49	-	ns
f <sub>data</sub>	data rate		[3]	-	20	-	20	-	20	Mbps

<sup>[1]</sup>  $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .  $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ .

<sup>[2]</sup> Delay between OE going LOW and when the outputs are disabled.

<sup>[3]</sup> Assuming a maximum one-shot accelerator pulse length of 50ns and equal time for 1 and 0 bit information

## 4-bit dual supply translating transceiver; open drain; auto direction sensing

Table 12. Dynamic characteristics for temperature range -40 °C to +125 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit, see Figure 6; for wave forms, see Figure 4 and Figure 5.

Symbol	Parameter	Conditions		V <sub>CC(B)</sub>									
				2.	5 V	3.	3 V	5.0	0 V				
V <sub>CC(A)</sub> = t <sub>PHL</sub> t <sub>PHL</sub> t <sub>PLH</sub> t <sub>PLH</sub> t <sub>en</sub> t <sub>dis</sub> t <sub>TLH</sub> t <sub>THL</sub>				Min	Max	Min	Max	Min	Max				
V <sub>CC(A)</sub> =	1.8 V							•					
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B		-	5.8	-	5.9	-	7.3	ns			
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B		-	8.5	-	8.5	-	8.8	ns			
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A		-	5.5	-	5.7	-	5.9	ns			
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A		-	6.7	-	5.7	-	1.4	ns			
t <sub>en</sub>	enable time	OE to A; B		-	200	-	200	-	200	ns			
t <sub>dis</sub>		OE to A; no external load	[2]	-	100	-	100	-	100	ns			
		OE to B; no external load	[2]	-	100	-	100	-	100	ns			
(		OE to A		-	250	-	250	-	250	ns			
	HIGH to LOW propagation delay LOW to HIGH propagation delay enable time disable time  LOW to HIGH output transition time  HIGH to LOW output transition time pulse width data rate  LOW to HIGH to LOW propagation delay LOW to HIGH propagation delay	OE to B		-	220	-	220	-	220	ns			
t <sub>TLH</sub>	LOW to HIGH	A port		3.2	11.9	1.2	11.7	1.1	9.5	ns			
	-	B port		3.3	13.5	2.7	14.5	2.7	13.5	ns			
t <sub>THL</sub>		A port		1.2	7.4	1.0	7.5	1.0	16.7	ns			
	•	B port		2.6	9.5	2.2	9.4	2.8	12.5	ns			
t <sub>W</sub>	pulse width	data inputs		49	-	49	-	49	-	ns			
			[3]	-	20	-	20	-	20	Mbps			
	HIGH to LOW	A to B		-	4.0	-	4.2	-	4.3	ns			
t <sub>PLH</sub>		A to B		-	4.4	-	5.2	-	5.5	ns			
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A		-	3.8	-	4.5	-	5.4	ns			
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A		-	3.2	-	2.0	-	1.5	ns			
t <sub>en</sub>	enable time	OE to A; B		-	200	-	200	-	200	ns			
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	100	-	100	-	100	ns			
		OE to B; no external load	[2]	-	100	-	100	-	100	ns			
		OE to A		-	220	-	220	-	220	ns			
		OE to B		-	220	-	220	-	220	ns			
t <sub>TLH</sub>	LOW to HIGH	A port		2.8	10	1.4	8.3	1.2	7.8	ns			
	output transition time	B port		3.2	10.4	2.9	15.5	2.4	16.9	ns			
t <sub>THL</sub>	HIGH to LOW	A port		1.0	7.2	1.0	6.9	1.0	6.7	ns			
	output transition	B port		2.2	9.8	2.4	8.4	2.6	8.3	ns			

## 4-bit dual supply translating transceiver; open drain; auto direction sensing

Table 12. Dynamic characteristics for temperature range -40 °C to +125 °C[1] ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit, see Figure 6; for wave forms, see Figure 4 and Figure 5.

Symbol	Parameter	Conditions				Vc	C(B)			Unit
				2.	5 V	1	3 V	5.0	0 V	
				Min	Max	Min	Max	Min	Max	
t <sub>W</sub>	pulse width	data inputs		49	-	49	-	49	-	ns ms ns
f <sub>data</sub>	data rate		[3]	-	20	-	20	-	20	Mbps
V <sub>CC(A)</sub> =	3.3 V							1	-	
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B		-	-	-	3.0	-	3.9	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B		-	-	-	5.3	-	5.5	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	B to A		-	-	-	3.2	-	4.2	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	B to A		-	-	-	3.2	-	3.3	ns
t <sub>en</sub>	enable time	OE to A; B		-	-	-	200	-	200	ns
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	100	-	100	ns
		OE to B; no external load	[2]	-	-	-	100	-	100	ns
		OE to A		-	-	-	280	-	280	ns
		OE to B		-	-	-	220	-	220	ns
t <sub>TLH</sub>	LOW to HIGH	A port		-	-	1.2	13.1	1.1	7.4	ns
	output transition time	B port		-	-	2.5	14.2	2.1	16.0	ns
t <sub>THL</sub>		A port		-	-	1.0	6.8	1.0	6.3	ns
output transition time		B port		-	-	2.3	9.3	2.4	9.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	49	-	49	-	ns
f <sub>data</sub>	data rate		[3]	-	-	-	20	-	20	Mbps

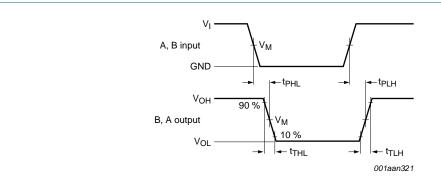
<sup>[1]</sup>  $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .  $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ .

<sup>[2]</sup> Delay between OE going LOW and when the outputs are disabled.

<sup>[3]</sup> Assuming a maximum one-shot accelerator pulse length of 50ns and equal time for 1 and 0 bit information

4-bit dual supply translating transceiver; open drain; auto direction sensing

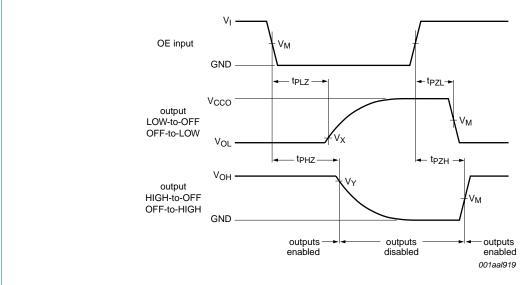
### 13. Waveforms



Measurement points are given in Table 13.

V<sub>OL</sub> and V<sub>OH</sub> are typical output voltage levels that occur with the output load.

Fig 4. The data input (A, B) to data output (B, A) propagation delay times



Measurement points are given in Table 13.

V<sub>OL</sub> and V<sub>OH</sub> are typical output voltage levels that occur with the output load.

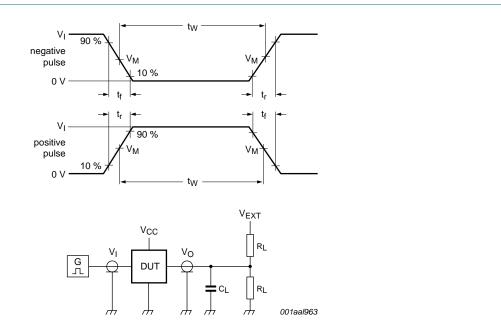
Fig 5. Enable and disable times

## 4-bit dual supply translating transceiver; open drain; auto direction sensing

Table 13. Measurement points[1][2]

Supply voltage	Input	Output		
V <sub>cco</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>
0.95 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> – 0.1 V
1.8 V ± 0.15 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
2.5 V ± 0.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
$3.3~\text{V}\pm0.3~\text{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> – 0.3 V
5.0 V ± 0.5 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> – 0.3 V

- [1]  $V_{CCI}$  is the supply voltage associated with the input.
- [2]  $V_{CCO}$  is the supply voltage associated with the output.



Test data is given in Table 14.

All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  10 MHz; Z<sub>0</sub> = 50  $\Omega$ ; dV/dt  $\geq$  1.0 V/ns.

R<sub>L</sub> = Load resistance.

C<sub>L</sub> = Load capacitance including jig and probe capacitance.

V<sub>EXT</sub> = External voltage for measuring switching times.

Fig 6. Test circuit for measuring switching times

Table 14. Test data

Supply voltage	)	Input		Load		V <sub>EXT</sub>		
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	V <sub>I</sub> [1]	∆t/∆V	CL	R <sub>L</sub> [2]	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]
0.95 V to 3.6 V	1.65 V to 5.5 V	$V_{CCI}$	≤ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>

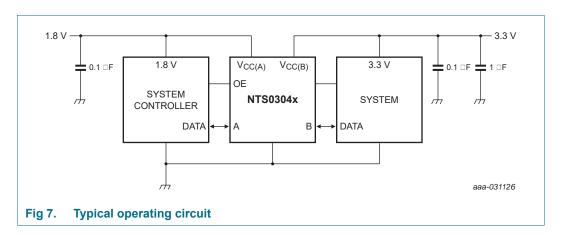
- [1] V<sub>CCI</sub> is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements,  $R_L$  = 1 M $\Omega$ . For measuring enable and disable times,  $R_L$  = 50 K $\Omega$ .
- [3]  $V_{\text{CCO}}$  is the supply voltage associated with the output.

4-bit dual supply translating transceiver; open drain; auto direction sensing

### 14. Application information

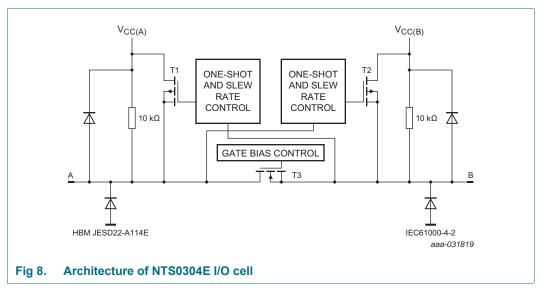
### 14.1 Applications

Voltage level-translation applications. The NTS0304E can be used in point-to-point applications to interface between devices or systems operating at different supply voltages. The device is primarily targeted at I<sup>2</sup>C or 4-wire which use open-drain drivers. It may also be used in applications where push-pull drivers are connected to the ports, however the NTB010x or the newer lower voltage NTB030x series of devices are more suitable.



#### 14.2 Architecture

The architecture of the NTS0304E is shown in <u>Figure 8</u>. The device does not require an extra input signal to control the direction of data flow from A to B or B to A.



The NTS0304E is a "switch" type voltage translator, it employs two key circuits to enable voltage translation:

1. A pass-gate transistor (N-channel) that ties the ports together.

## 4-bit dual supply translating transceiver; open drain; auto direction sensing

2. An output edge-rate accelerator that detects and accelerates rising edges on the I/O pins.

The gate bias voltage of the pass gate transistor (T3) is set at approximately one threshold voltage above the V<sub>CC</sub> level of the low-voltage side. During a LOW-to-HIGH transition, the output one-shot accelerates the output transition by switching on the PMOS transistors (T1, T2). It bypasses the 10 k $\Omega$  pull-up resistors and increases the current drive capability. The one-shot is activated once the input transition reaches approximately V<sub>CCI</sub>/2; it is deactivated approximately 50 ns after the output reaches V<sub>CCO</sub>/2. During the acceleration time, the driver output resistance is between approximately 50  $\Omega$  and 70  $\Omega$ . To avoid signal contention and minimize dynamic I<sub>CC</sub>, the user should wait for the one-shot circuit to turn-off before applying a signal in the opposite direction. Pull-up resistors are included in the device for DC current sourcing capability.

#### 14.3 Input driver requirements

As the NTS0304E is a switch type translator, properties of the input driver directly effect the output signal. The external open-drain or push-pull driver applied to an I/O determines the static current sinking capability of the system. The max data rate, HIGH-to-LOW output transition time ( $t_{THL}$ ), and propagation delay ( $t_{PHL}$ ), are dependent upon the output impedance and edge-rate of the external driver. The limits provided for these parameters in the data sheet assume a driver with output impedance below 50  $\Omega$  is used.

#### 14.4 Output load considerations

The maximum lumped capacitive load that can be driven is dependent upon the one-shot pulse duration. In cases with very heavy capacitive loading, there is a risk that the output does not reach the positive rail within the one-shot pulse duration. The NTS0304E has a longer one-shot pulse for driving larger capacitive loads.

To avoid excessive capacitive loading and to ensure correct triggering of the one-shot, use short trace lengths and low capacitance connectors on NTS0304E PCB layouts. The length of the PCB trace should be such that the round-trip delay of any reflection is within the one-shot pulse duration (approximately 50 ns). It ensures low impedance termination and avoids output signal oscillations and one-shot retriggering.

#### 14.5 Output single shot slew rate control

Integrated slew-rate control and timed increase of the one-shot driver output current reduce EMI. An additional comparator circuit on the  $V_{OUT}$  side starts to reduce the one-shot driver current when  $V_{OUT} > 0.65 V_{OUT}$  with a slight delay, so it can safely drive the output voltage to a safe high-level while at the same time reducing the driver strength early enough to reduce overshoots and ringing.

#### 14.6 Power-up

During operation,  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ . However, during power-up,  $V_{CC(A)} \ge V_{CC(B)}$  does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NTS0304E includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

4-bit dual supply translating transceiver; open drain; auto direction sensing

#### 14.7 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{\rm dis}$  with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time ( $t_{\rm en}$ ) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor. The current-sourcing capability of the driver determines the minimum value of the resistor.

#### 14.8 Pull-up or pull-down resistors on I/Os lines

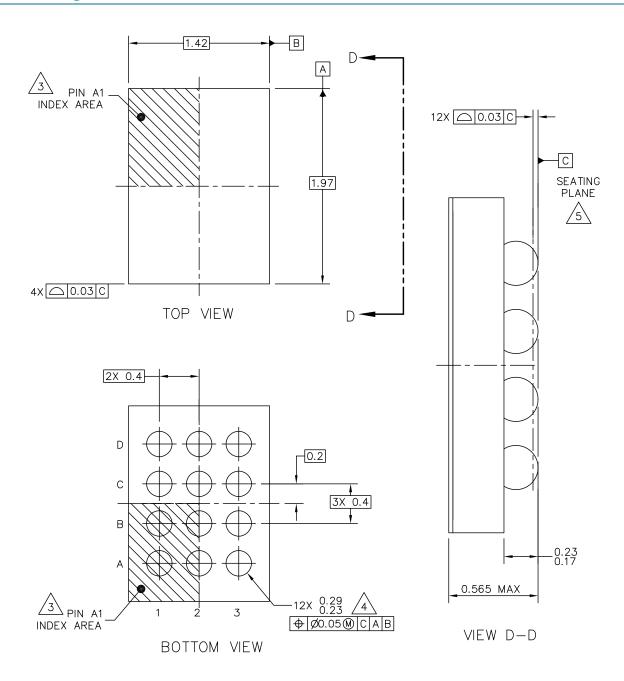
The A port I/O has an internal 10  $k\Omega$  pull-up resistor to  $V_{CC(A)}$ . The B port I/O has an internal 10  $k\Omega$  pull-up resistor to  $V_{CC(B)}$ . If a smaller value of pull-up resistor is required, add an external resistor in parallel to the internal 10  $k\Omega$ . This pull-up resistor effects the  $V_{OL}$  level. When OE goes LOW, the internal pull-ups of the NTS0304E are disabled.

#### 14.9 ESD protection on I/Os lines

The NTS0304E contains rail to rail ESD protection structures connecting the A and B I/O to their respective supply. As a consequence, if a supply pin is pulled low, the related I/Os are pulled low too through the upper ESD protection diode and the 10 k $\Omega$  pull-up resistor. Additionally, besides the normal HBM and CDM ESD protection features on both A and B Port I/O the B Port I/O features integrated ESD protection to IEC 61000-4-2 Class 4 system ESD level of 8kV contact for when users plug cameras, games, and other items into their USB or video ports in real-world ESD stress applications.

4-bit dual supply translating transceiver; open drain; auto direction sensing

## 15. Package outline



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MECHANICAL OUTLINE	STANDARD:	DRAWING NUMBER:	REVISION:	PAGE:		
PRINT VERSION NOT TO SCALE	NON JEDEC	98ASA01259D	0			

Fig 9. Package outline SOT1390-10 (WLCSP12) 1 of 2

## 4-bit dual supply translating transceiver; open drain; auto direction sensing

#### NOTES:

- 1. ALL DIMENSIONS IN MILLIMETERS.
- 2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.

3. PIN A1 FEATURE SHAPE, SIZE AND LOCATION MAY VARY.

MAXIMUM SOLDER BALL DIAMETER MEASURED PARALLEL TO DATUM C.

5.\ DATUM C, THE SEATING PLANE, IS DETERMINED BY THE SPHERICAL CROWNS OF THE SOLDER BALL

6. THIS PACKAGE HAS A BACK SIDE COATING THICKNESS OF 0.025.

© NXP B.V. ALL RIG		DATE:19	JUNE 2018	
MECHANICAL OUTLINE	STANDARD:	DRAWING NUMBER:	REVISION:	PAGE:
PRINT VERSION NOT TO SCALE	NON JEDEC	98ASA01259D	0	

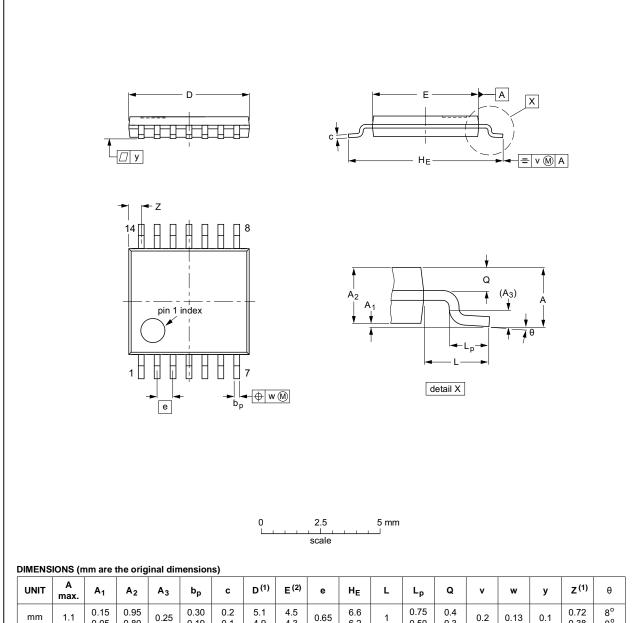
Fig 10. Package outline SOT1390-10 (WLCSP12) 2 of 2

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4-bit dual supply translating transceiver; open drain; auto direction

TSSOP14: plastic thin shrink small outline package; 14 leads; body width 4.4 mm

SOT402-1



UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	bp	С	D <sup>(1)</sup>	E (2)	е	HE	L	Lp	Q	v	w	у	Z <sup>(1)</sup>	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	5.1 4.9	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.72 0.38	8° 0°

#### Notes

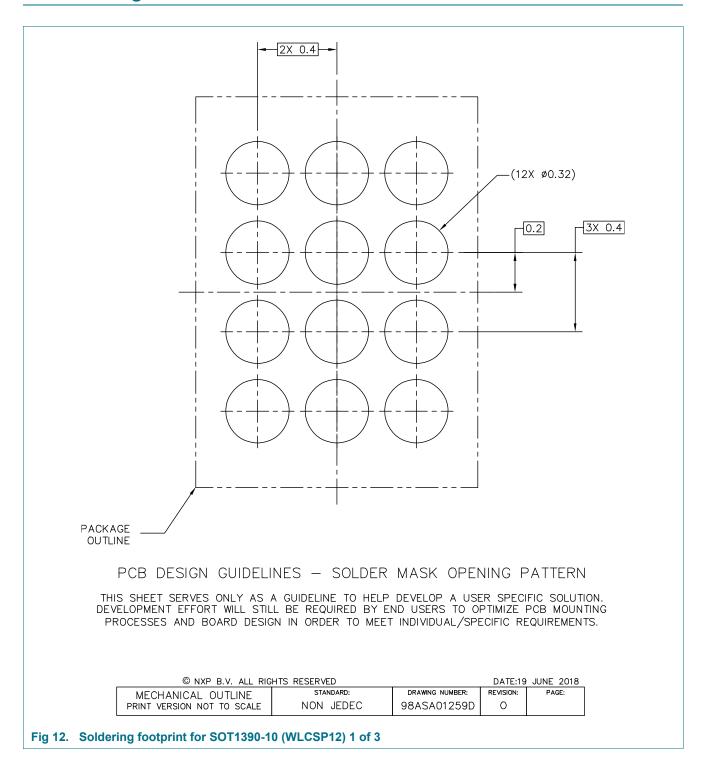
- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	ENCES	EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	JEITA	PROJECTION	ISSUE DATE	
SOT402-1		MO-153			<del>99-12-27</del> 03-02-18	

Fig 11. NTS0304E Package outline SOT402-1 (TSSOP14)

4-bit dual supply translating transceiver; open drain; auto direction sensing

### 16. Soldering



## 4-bit dual supply translating transceiver; open drain; auto direction sensing

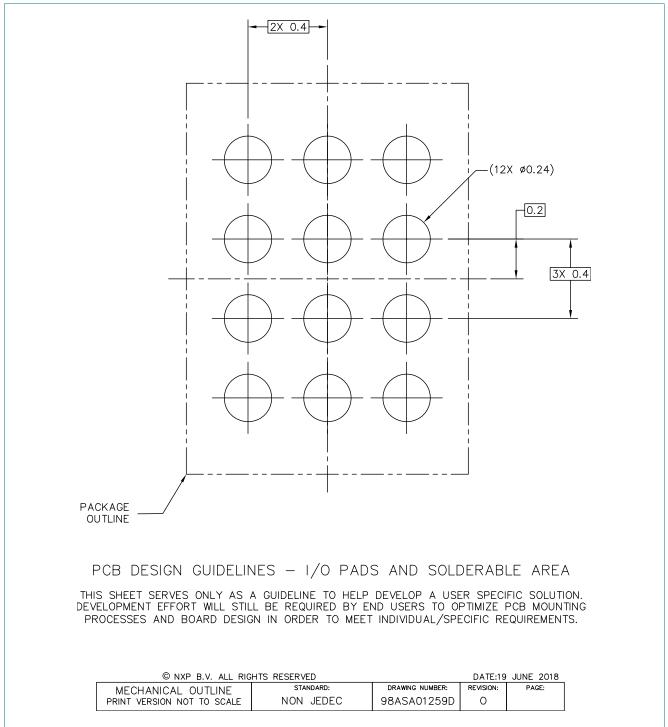
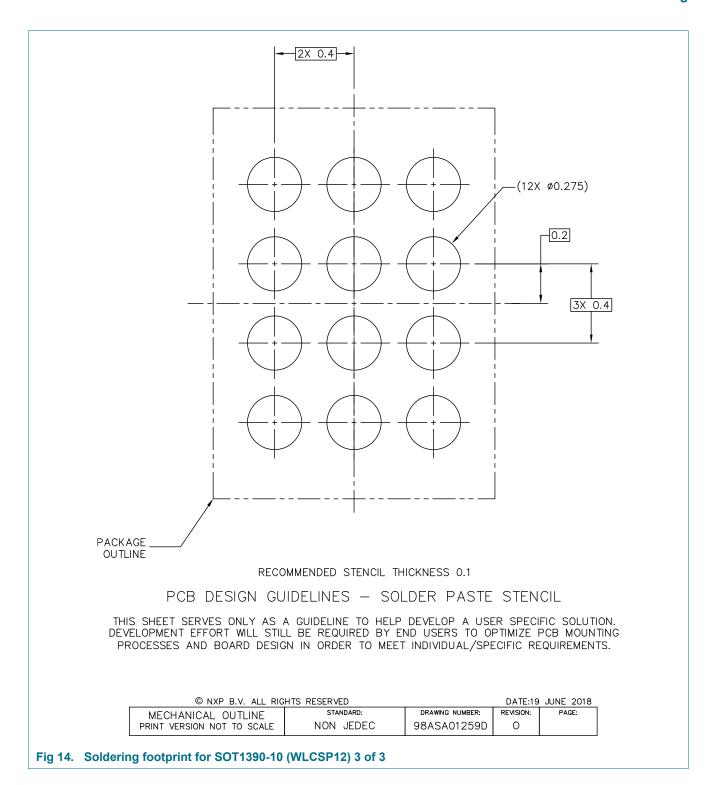


Fig 13. Soldering footprint for SOT1390-10 (WLCSP12) 2 of 3

## 4-bit dual supply translating transceiver; open drain; auto direction sensing



NTS0304E

4-bit dual supply translating transceiver; open drain; auto direction sensing

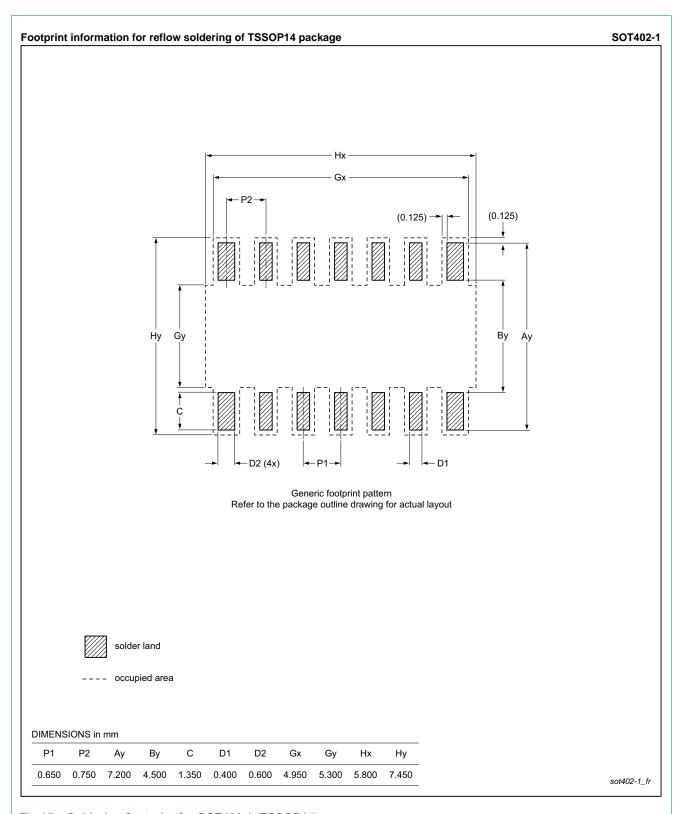


Fig 15. Soldering footprint for SOT402-1 (TSSOP14)

4-bit dual supply translating transceiver; open drain; auto direction sensing

### 17. Abbreviations

#### Table 15. Abbreviations

Description
Charged Device Model
Device Under Test
ElectroStatic Discharge
General Purpose Input Output
Human Body Model
Inter-Integrated Circuit
International Electrotechnical Commission
Machine Model
Printed-Circuit Board
Positive Metal Oxide Semiconductor
System Management Bus
Universal Asynchronous Receiver Transmitter

## 18. Revision history

#### Table 16. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
NTS0304E v.1.0	20190201	Product data sheet	-	-

## 4-bit dual supply translating transceiver; open drain; auto direction sensing

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Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

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- [2] The term 'short data sheet' is explained in section "Definitions"
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## 4-bit dual supply translating transceiver; open drain; auto direction sensing

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## 4-bit dual supply translating transceiver; open drain; auto direction sensing

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