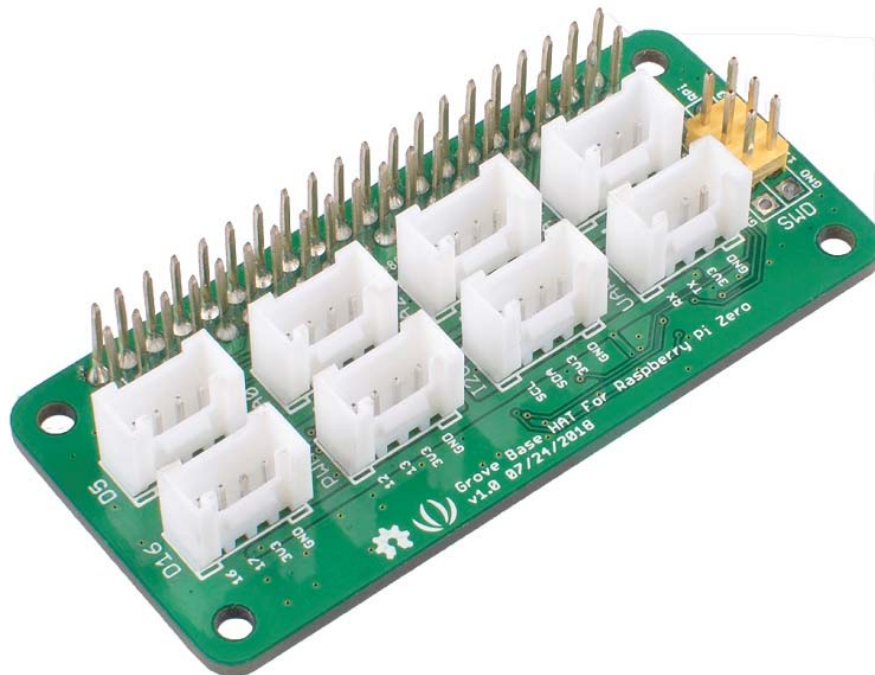


Grove Base Hat for Raspberry Pi Zero



Today, the grove series of sensors, actuators, and displays have grown into a large family. More and more grove modules will join the whole Grove ecosystem in the future. We see the Grove helps makers, engineers, teachers, students and even artists to build, to make, to create...We always feel it is our responsibility to make the Grove module compatible with more platforms. Now we bring you the Grove Base Hat for Raspberry Pi and Grove Base Hat for Raspberry Pi Zero, in another word, we bring the Raspberry Pi the whole Grove System.

The Grove Base Hat for Raspberry Pi provide Digital/Analog/I2C/PWM/UART port to meet all your needs. With the help of build-in MCU, a 12-bit 6 channel ADC is also available for Raspberry Pi.

Frankly speaking, it's about 60 Grove modules support the Grove Base Hat for Raspberry Pi now. However, we will continue to add new compatible modules, the more you use, the more grove added.

Features

- Support Raspberry 2/ 3 B/B+ Zero
- build-in MCU
- 12-bit ADC
- Multi-type Grove port

Specification

Item	Value
Operating Voltage	3.3V
MCU	STM32
ADC	12-bit 6 channel
Grove Port	2 Digital 3 Analog 1 I2C 1 PWM 1 UART
Raspberry pi communication bus	I2C
I2C Address	0x04

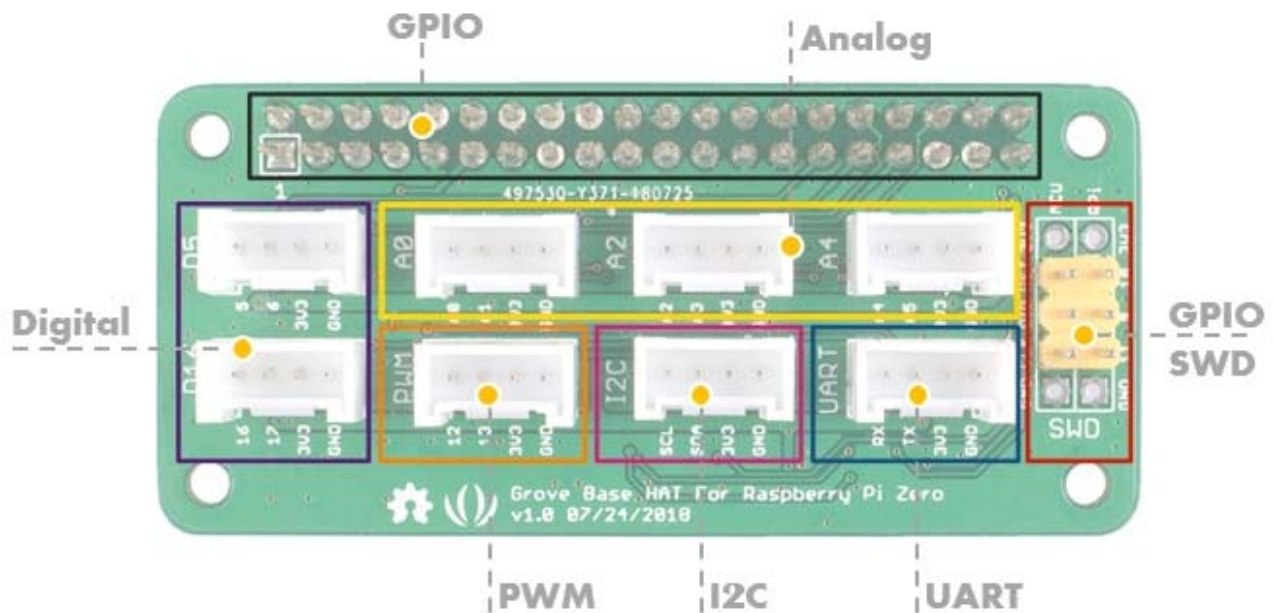
Attention

The operating voltage is 3.3V, please do not input more than 3.3V, otherwise it may damage the Raspberry Pi. Moreover, this hat can not work with 5V grove module via grove port, please use 3.3V compatible Grove module.

Hardware Overview

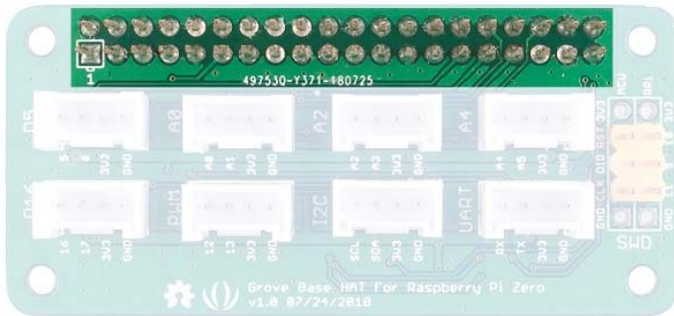
Pin Out

Overview



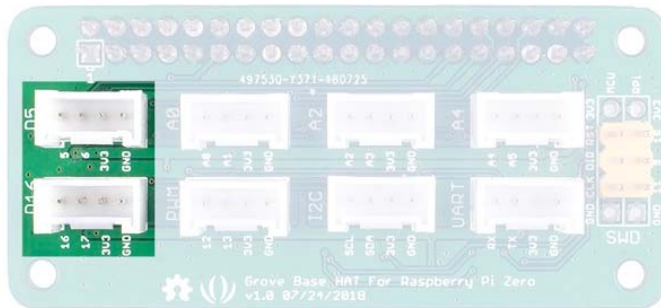
GPIO

The same pin out as the raspberry pi.



Digital

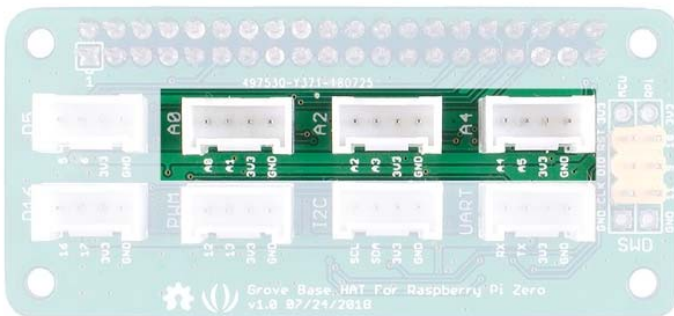
There are 2 digital Grove sockets in this board, normally the yellow wire(which connect to the top pin of the 4 pins Grove socket as) of Grove cable is the signal wire, so we name the digital Grove port **D5/D16**.



Analog

As we know, there is no ADC in the Raspberry Pi, so it can not work with analog sensor directly. Now with the help of the build-in MCU STM32, the Grove base hat can work as an external 12-bit ADC, which means you can use analog sensor with your Raspberry Pi. Even more pleasing is that not one but four analog Grove sockets are available.

The analog sensor inputs the analog voltage into the 12-bit ADC. After the ADC convert the analog data to digital data, it input the digital data to the Raspberry Pi through the I2C interface.



PWM(pulse-width modulation)

The Grove PWM Port connect to GPIO/BCM pin12(PWM0) and GPIO/BCM pin13(PWM1), which is the hardware PWM pin of Raspberry Pi, in addition, you can use all the GPIO pin as the soft PWM pin.

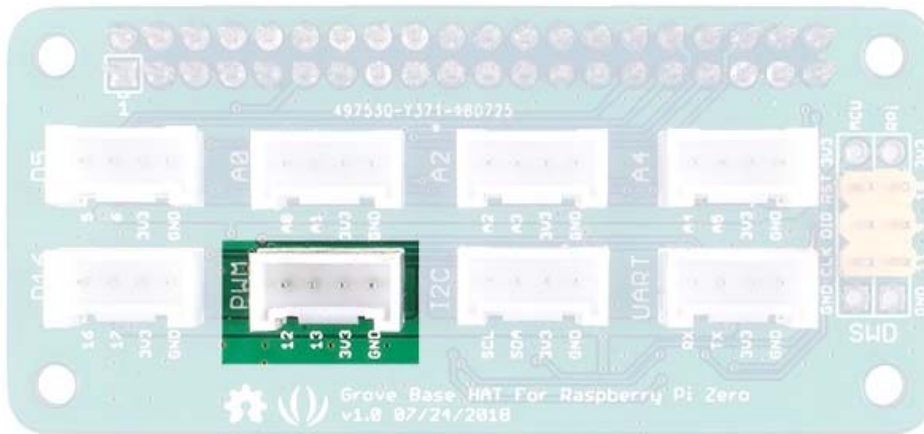
Note

0- All the silkscreen layer pin number besides the Grove port is the BCM pin number. The difference between BCM pins and the physical pins please refer to [here](#)

1- Compared with hardware PWM, the software PWM isn't so accurate and will have trouble at high frequencies.

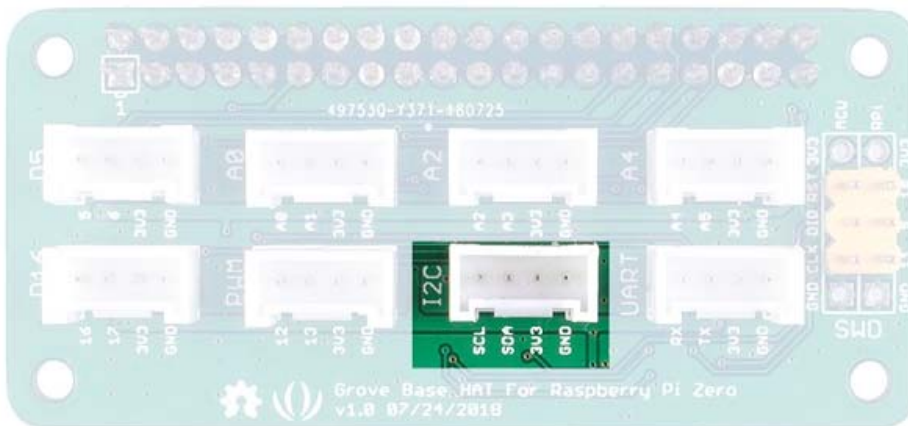
2- The GPIO/BCM pin18 is also marked as PWM0, actually the GPIO/BCM 12 and the GPIO/BCM 18 share the same PWM channel, so they can't set to different rate.

3- The audio jack output also uses PWM 0 and PWM 1, so you can't have audio output on that socket and use the PWMs at the same time.



I2C

The Grove I2C port connect to the I2C pin of the raspberry directly. Most of seeed's new grove modules have I2C interface, you may find this port is extremely useful.



Warning

We recommend that you power up the Raspberry Pis after all the hardware connections are complete. Please do not hot plug the sensor module, otherwise the Raspberry Pi may crash.

Software

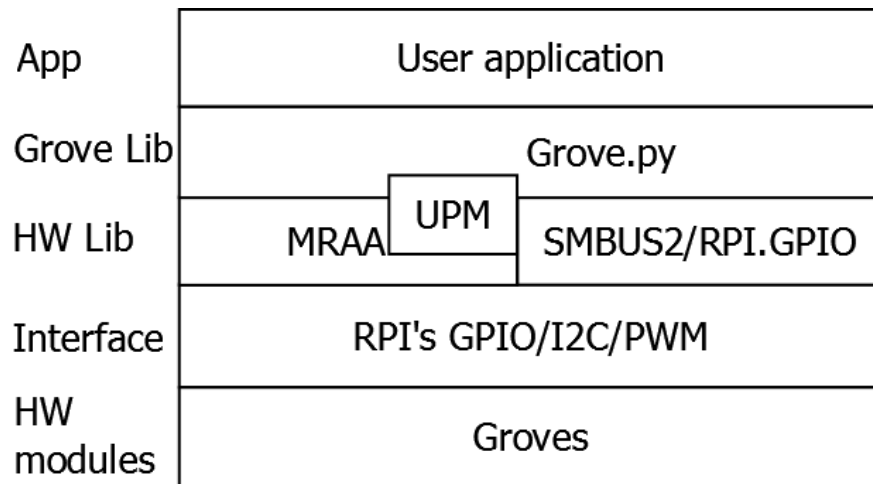
In this section we will introduce how to install the **seeed grove.py** library and how to use I2C, PWM, Digital and analog port of the Grove Base Hat for Raspberry Pi Zero.

Tip

If you do not know how to use a raspberry pi, please check [here](#) before start.

Architecture

To operate grove sensors, the grove.py depends many hardware interface libraries such as mraa/smbus2/rpi.gpi/rpi_ws281x.



Online one-click installation

One-click installation, quick start, what ever you call, with the single command below, we can install/update all dependencies and latest grove.py.

```
1 curl -sL https://github.com/Seeed-Studio/grove.py/raw/master/install.sh |  
  sudo bash -s -
```

Success

if everything goes well, you will see the following notice.

```
1 Successfully installed grove.py-0.5  
2 #####  
3 Latest Grove.py from github install complete !!!!!  
4 #####
```

Step by step installation

Besides the one-click installation, you can also install all the dependencies and latest grove.py step by step. Please refer to our github page for more information.

[Step by step installation](#)

You can check the source file by cloning the grove.py library.

```
1 git clone https://github.com/Seeed-Studio/grove.py
```

Usage

Now you can use the Grove Base Hat for Raspberry Pi Zero with dozens Grove modules, tap the command **grove_** and press the Tab key to check the supported Grove list.

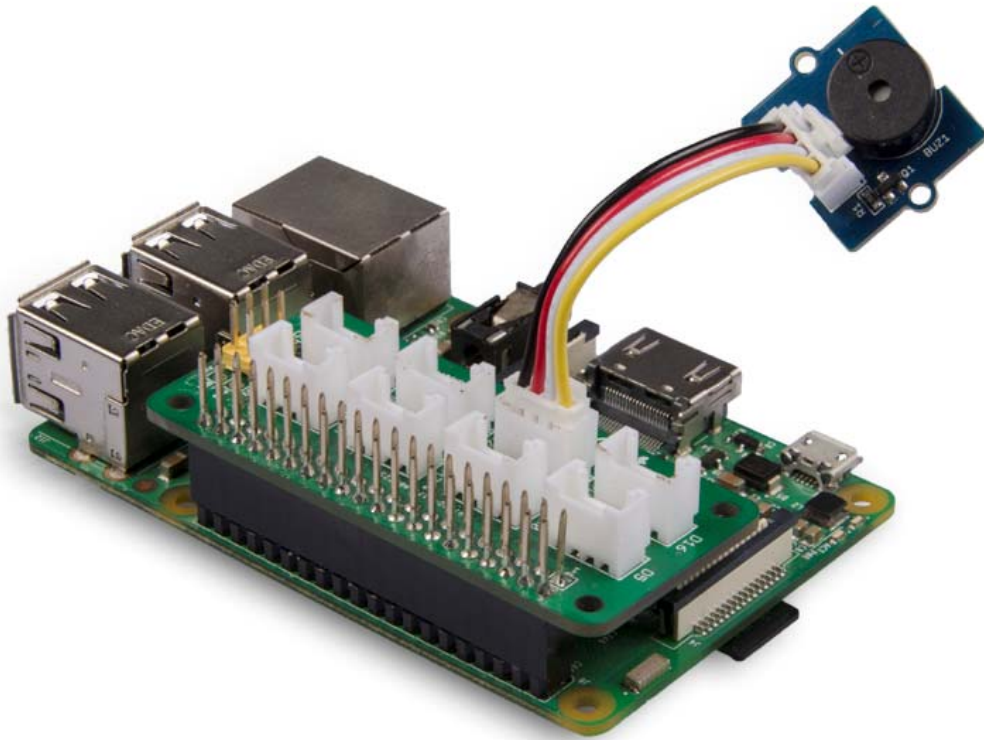
```
1 pi@raspberrypi:~$ grove_  
2 grove_3_axis_compass_bmm150          grove_i2c_color_sensor_v2  
3 grove_mini_pir_motion_sensor         grove_rotary_angle_sensor  
4 grove_temperature_sensor  
5 grove_4_digit_display                grove_i2c_motor_driver  
6 grove_moisture_sensor                 grove_ryb_led_button  
7 grove_thumb_joystick  
8 grove_air_quality_sensor_v1_3        grove_lcd_1.2inches  
9 grove_oled_display_128x64           grove_servo  
   grove_tilt_switch  
   grove_button                        grove_led  
   grove_piezo_vibration_sensor        grove_slide_potentiometer  
   grove_touch_sensor  
   grove_collision_sensor              grove_light_sensor_v1_2  
   grove_pwm_buzzer                    grove_sound_sensor  
   grove_ultrasonic_ranger  
   grove_gesture_sensor                grove_loudness_sensor  
   grove_recorder_v3_0                 grove_switch  
   grove_water_sensor  
   grove_high_accuracy_temperature    grove_mech_keycap  
   grove_relay                          grove_temperature_humidity_sensor  
pi@raspberrypi:~$ grove_
```

Then we will show you how to use them according to port type.

PWM Port

We will take the [Grove - buzzer](#) for example to introduce the PWM port.

Hardware connection diagram



Tap the following command `sudo grove_pwm_buzzer` in the command line interface.

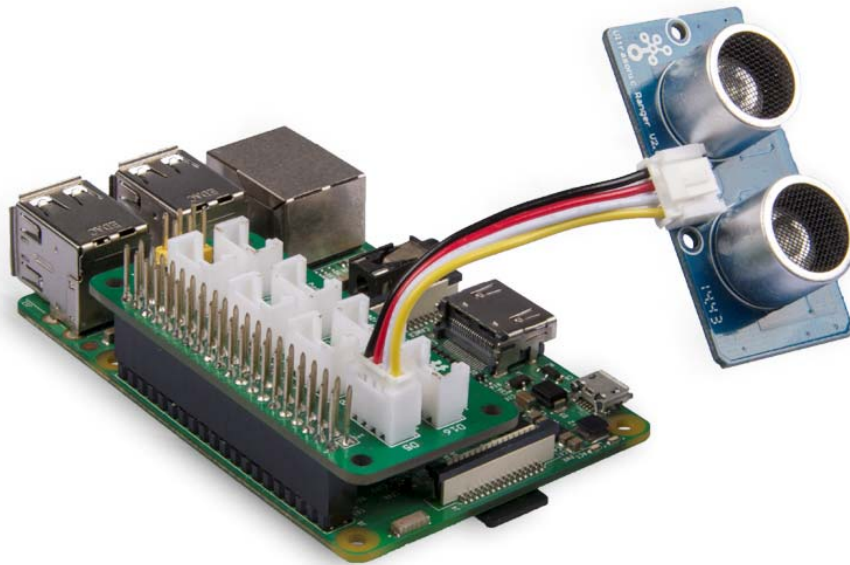
```
lpi@raspberrypi:~$ sudo grove_pwm_buzzer
2 Insert Grove-Buzzer to Grove-Base-Hat slot PWM[12 13 VCC GND]
3
4 3800
5 3400
6 3000
7 2900
8 2550
9 2270
10 2000
11 exiting application
```

The buzzer will ring a few times and then stop, the program will automatically exit.

Digital Port

We will take the [Grove - Ultrasonic Ranger](#) for example to introduce the Digital port.

Hardware connection diagram



Tap the following command `grove_ultrasonic_ranger 5 6` in the command line interface.

```
1 pi@raspberrypi:~$ grove_ultrasonic_ranger 5 6
2 Detecting distance...
3 6.979909436456088 cm
4 7.966469074117726 cm
5 12.451204760321255 cm
6 15.184797089675378 cm
7 17.429220265355603 cm
8 18.73230112010035 cm
9 20.717752390894397 cm
10 19.83807004731277 cm
11 17.3059003106479 cm
12
13 ^CTraceback (most recent call last):
14   File "/usr/local/bin/grove_ultrasonic_ranger", line 11, in <module>
15     load_entry_point('grove.py==0.5', 'console_scripts',
16 'grove_ultrasonic_ranger')()
17   File "/usr/local/lib/python3.5/dist-
18 packages/grove/grove_ultrasonic_ranger.py", line 107, in main
19     time.sleep(1)
KeyboardInterrupt
```

When you change the distance between the Grove - Ultrasonic Ranger and the target object, the measurement value will change accordingly. Press `Ctrl+C` to quit.

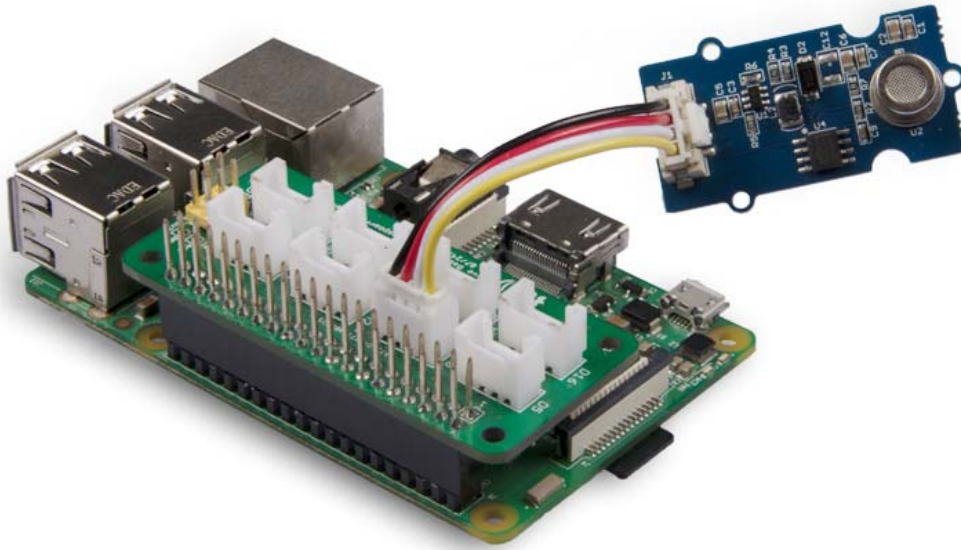
Attention

For most grove module, you need to add the pin number parameter, like `grove_ultrasonic_ranger 5 6`, `5` and `6` are the GPIO/BCM pin. However, you may have noticed that in the first example `grove_pwm_buzzer`, we didn't add a parameter after the command. This is because the PWM port and I2C port do not require pin number parameters. You can find the pin number silkscreen just besides the Grove socket.

Analog Port

We will take the [Grove - Air quality sensor v1.3](#) for example to introduce the Analog port.

Hardware connection diagram



Tap the following command `grove_air_quality_sensor_v1_3 0 1` in the command line interface.

```
1 pi@raspberrypi:~$ grove_air_quality_sensor_v1_3 0 1
2 Detecting ...
3 62, Air Quality OK.
4 63, Air Quality OK.
5 61, Air Quality OK.
6 61, Air Quality OK.
7 59, Air Quality OK.
8 62, Air Quality OK.
9 60, Air Quality OK.
10 60, Air Quality OK.
11 59, Air Quality OK.
12 60, Air Quality OK.
13 60, Air Quality OK.
14 60, Air Quality OK.
15
16 57, Air Quality OK.
17 ^CTraceback (most recent call last):
18   File "/usr/local/bin/grove_air_quality_sensor_v1_3", line 11, in <module>
19     load_entry_point('grove.py==0.5', 'console_scripts',
20 'grove_air_quality_sensor_v1_3')()
21   File "/usr/local/lib/python3.5/dist-
22 packages/grove/grove_air_quality_sensor_v1_3.py", line 68, in main
    time.sleep(.1)
KeyboardInterrupt
```

You can use this sensor to detect the air quality. Press `Ctrl+C` to quit.

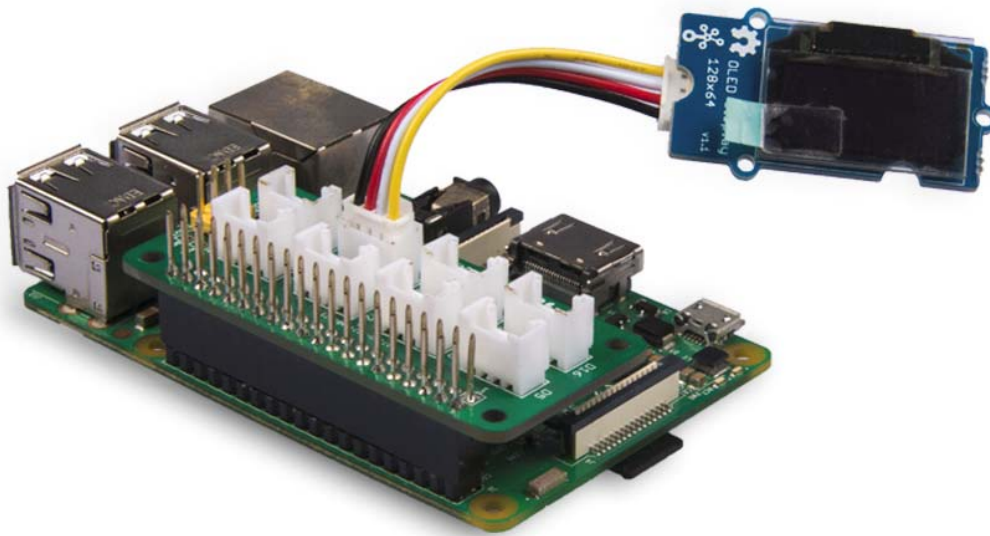
Notice

You may have noticed that for the analog port, the silkscreen pin number is something like **A1**, **A0**, however in the command we use parameter **0** and **1**, just the same as digital port. So please make sure you plug the module into the correct port, otherwise there may be pin conflicts.

I2C

We will take the [Grove - OLED Display 128x64](#) for example to introduce the I2C port.

Hardware connection diagram



Tap the following command `grove_oled_display_128x64` in the command line interface.

```
1 pi@raspberrypi:~$ grove_oled_display_128x64
2 pi@raspberrypi:~$
```

It seems nothing happened, however you can find the most famous sentence in the cyber world if you check your oled.☺

Note

If you use the I2C tool to scan the I2C address of the grove module, you may find two or more address. `0x04` is the address of the *Grove Base Hat for Raspberry Pi*.

Tech Support

Please do not hesitate to submit the issue into our forum

http://wiki.seeedstudio.com/Grove_Base_Hat_for_Raspberry_Pi_Zero/ 12-4-18