

MTi-7

The MTi-7 GNSS/INS module is a new miniature motion tracking module with multiple GNSS receiver support, making it the smallest GNSS/INS module using advanced sensor fusion algorithms. With its miniature SMD form factor (12.1x12.1mm) and low power consumption it is ideal for upcoming technologies including drones, UAV's, smart farming, unmanned control, Internet of (Moving) Things and robotics.

Features

- Providing industry standard Arduino header compatible development kit
- High performance orientation, velocity and positioning using advanced sensor fusion algorithms
- Best in class hardware and firmware using same form factor
- Uniform software/hardware interface over product lifetime (no end of life)

Applications

- Navigation input for UAV flight control
- Navigation input for Ground Vehicles
- Outdoor mapping stabilization
- Hyperspectral cameras

Ordering information

Part Number	Output	Packing Method
MTI-7	GNSS/INS; GNSS data, inertial data, roll/pitch/yaw	Tray (containing 20 modules)
		Reel (containing 250 modules)
MTi-7-DK	MTi-7 Reference design	Development Kit

Supported GNSS Receivers

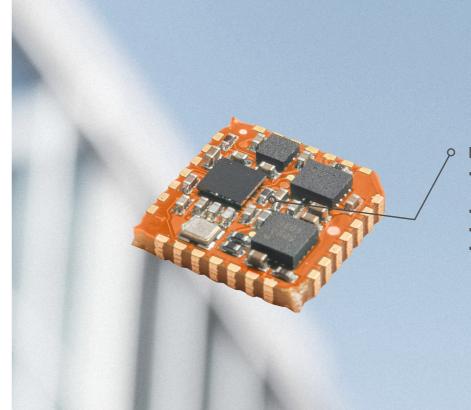
Manufacturer	GNSS Receiver	Protocol
uBlox	MAX-M8 series	UBX protocol (beta)
Generic	NEO-M8, ZED F9	NMEA input (GGA,GSA,GST,RMC)



Development Kit

In order to get started with the MTi-7, an extensive development kit for characterization and prototyping is available:

- Easy to use connection (micro USB), access to I2C/SPI/UART
- Arduino header compatible shield board
- Full functionality and pin configuration
- Intuitive MT Software Suite (Linux / Windows GUI)
- SDK with drivers and embedded software examples
- Shield board MTi-7, GNSS daughter card, GNSS antenna and USB cable



MTi-7

- Complete GNSS/INS module using existing GNSS infrastructure
- Best performing GNSS-aided AHRS
- Fully temperature calibrated module
- Miniature and lightweight SMD form factor with low power consumption

Specifications MTi-7

Orientation accuracy

Roll/Pitch (static)	0.5° 1 RMS
Roll/pitch (dynamic)	0.5° 1 RMS
Yaw (dynamic)	1.5° 1 RMS

Position and velocity (with MTi-7-DK)

Clock drift	1 ppm or external reference
Velocity 1 RMS	0.05 m/s
Vertical position 1 STD (SBAS, baro)	2.0 m
Horizontal position 1 STD (SBAS)	1.0 m

Inertial sensor performance

Gyroscope full-scale range	±2000°/s
Gyroscope bias stability	10 deg/hr
Gyroscope noise density	0.007°/s/√Hz
Gyroscope non-linearity	0.1% FS
Accelerometer full-scale range	±16 g
Accelerometer bias stability	0.03 mg
Accelerometer noise density	120 µg/√Hz
Accelerometer non-linearity	0.5% FS

Module specifications

Power consumption	<100 mW
nput voltage	2.19 to 3.6 V
Package	SMD, footprint compatible with JEDEC PLCC-28
Dize	12.1 x 12.1 x 2.55 mm
Veight	<1 g

Interfacing

Hardware interface	I2C, SPI, UART (selectable)
Software interface	Xsens Xbus binary protocol Driver source code supplied
Output data rate	0-800 Hz





ABOUT XSENS

Xsens is the leading innovator in 3D motion tracking technology and products. Its sensor fusion technologies enable a seamless interaction between the physical and the digital world in applications such as industrial control and stabilization, health, sports and 3D character animation. Clients and partners include Electronic Arts, NBC Universal, Daimler, Autodesk, ABB, Siemens and various other leading institutes and companies throughout the world. Xsens is part of mCube, the provider of the world's smallest MEMS motion sensors, key enablers for the Internet of Moving Things. Xsens has offices in Enschede, Los Angeles, Shanghai and Hong Kong.

Visit xsens.com/distributors for an overview of Xsens' worldwide distributor network



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